

# Compressive sensing in wireless mobile communication system at high data rate transmission

Narendra Shukla, Anil Kumar, A. K. Jaiswal, Sandeep Kr. Yadav

**Abstract**— In this paper, the use of compressive sensing in a mobile communication system is proposed in order to increase the data rates. The objective is to increase the data rates of current and possibly future generation mobile systems. In the proposed system the speech signal is sampled below the Nyquist rate by using compressive sensing. The compressed spectrum is then transmitted over the wireless system and successfully reconstructed at the receiver without losing any significant information. In the proposed communication system, first the speech signal is modelled in such a way that the input signal is sparse enough before applying compressive sensing. The sparse signal is multiplied by the predefined measurement matrix. The output of the compressive sensing module is then transmitted to the receiver.

**Index Terms**— Laplacian distribution, analysis and processing, the threshold spectrum, Impedance characteristics.

## I. INTRODUCTION

Compressive Sensing in Mobile Communication System The purpose of this research effort is to implement compressive sensing in a mobile system. By using compressive sensing techniques, the speech signal is preceded at the transmitter side which is being sent to the receiver through a wireless channel. As a result, a small number of samples are being transmitted, and this will increase the transmission data rates when compared to the current communication systems.

The following list points out some of the future work that needs to be done which will improve the advancement of mobile communication systems.

- Implementing compressive sensing in 3G and LTE mobile communication systems
- Parameters like noise, multipath effects and shadowing needed to be considered while measuring the output
- Different transformations need to be tested in order to find the most efficient one for this application
- Design a measurement matrix that will be optimum for speech signals.

At the receiver, the signal is perfectly reconstructed from a significant small number of measurements by using different optimization techniques such as l-norm or convex

optimization. The basic block diagram of the proposed systems are shown in Figure 1.

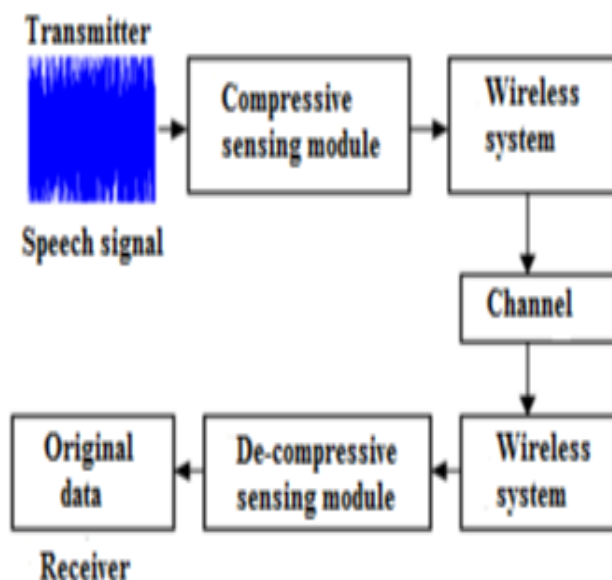


Figure 1. Compressive sensing in a mobile communication system

In the first stage of the project, a speech signal was modelled using a Laplace random number generator shown in Figure 2. It was decided to use a Laplace number generator to model the speech signal, because these types of signals typically have a Laplacian distribution [5]. The modelled speech signal was mapped into the discrete frequency domain using the FFT. The results obtained from this transformation are shown in Figure 3. In the second stage, before compressive sensing was applied to the signal, a threshold window was used to eliminate the coefficients that are significant to the signal. In other words, all the coefficients with small amplitude were multiplied by zero. In Figure 4 it can be seen how the FFT spectrum looks after the threshold has been applied. The purpose of the threshold is to ensure that the FFT spectrum is sparse.

## II. SPECTRUM ANALYSIS

In the third stage, the threshold spectrum was multiplied by the measurement matrix, which is a matrix composed of random numbers. The output of the compressive sensing algorithm is converted into a digital signal using an Analog-to-Digital converter in order to be transmitted by the mobile system.

Manuscript received August 07, 2013.

Narendra Shukla, Dept. of ECE, SHIATS, Allahabad, (U.P.), India.

Anil Kumar, Dept. of ECE, SHIATS, Allahabad, (U.P.), India.

A.K.Jaiswal, Dept. of ECE, SHIATS, Allahabad, (U.P.), India.

Sandeep Kr. Yadav, Dept. of ECE, SHIATS, Allahabad, (U.P.), India.

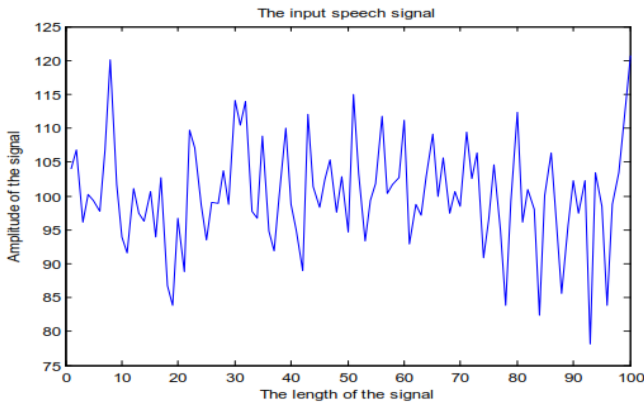


Figure 2. Input speech signal

At the receiver section, an initial guess was made using the measurement matrix and the observation vector (vector signal), which is close to the input speech signal. Finally, the speech signal was reconstructed from a significant small number of observations by using one of the optimization techniques available.

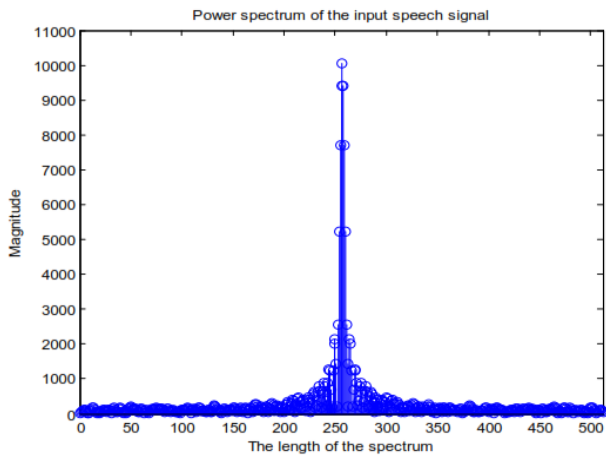


Figure 3. Power spectrum of the input speech signal

The reconstructed signal at the output of the optimization module is shown in Figure 8. The difference between the actual signal and the reconstructed signal was calculated in order to observe the error between both signals. This error is shown in Figure 6.

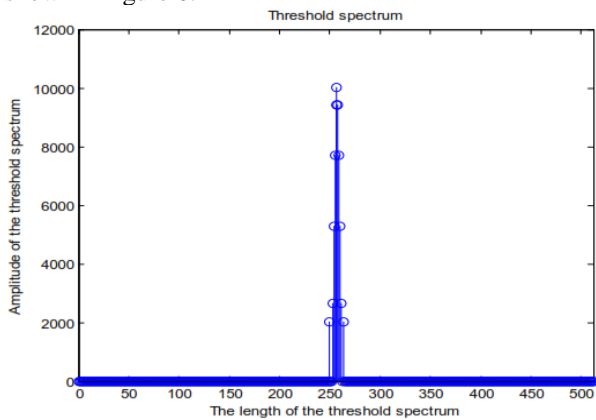


Figure 4. Threshold spectrum of FFT spectrum

The FFT was a revolutionary algorithm that made Fourier analysis and processing of digital signals fairly easy. The FFT algorithm employs a few tricks and can compute  $\log(N)$  operations [6]. There are two factors that need to be

considered when the FFT is implemented in MATLAB: the Fourier transform of a discrete signal in 2

- FFT uses complex numbers and
- It computes both positive and negative frequencies.

This is where it becomes difficult to implement FFT in compressive sensing.

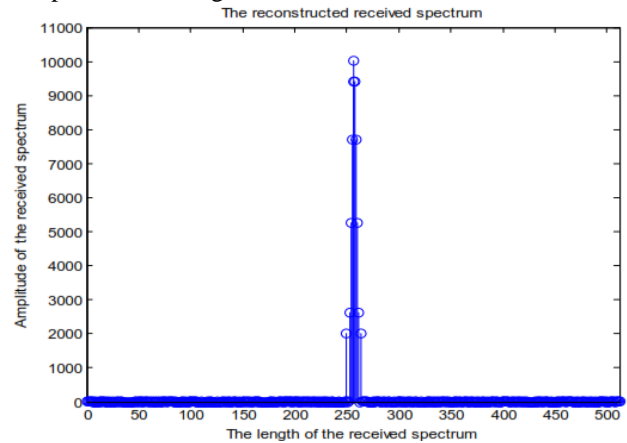


Figure 5. Reconstructed FFT spectrum using  $l_1$ -minimization

### III. ERROR DETECTION AND RECONSTRUCTION

The main problem is that applying compressive sensing to a complex number is a tedious and complex process, and is being researched at Michigan State University using a hybrid compressive sensing model (Complex and Real) [7]. In order to overcome caused by the FFT, instead a Discrete Cosine Transform (DCT) is implemented. The DCT is conceptually the same as DFT except that it does a better job in concentrating the energy into lower order coefficients than the DFT.

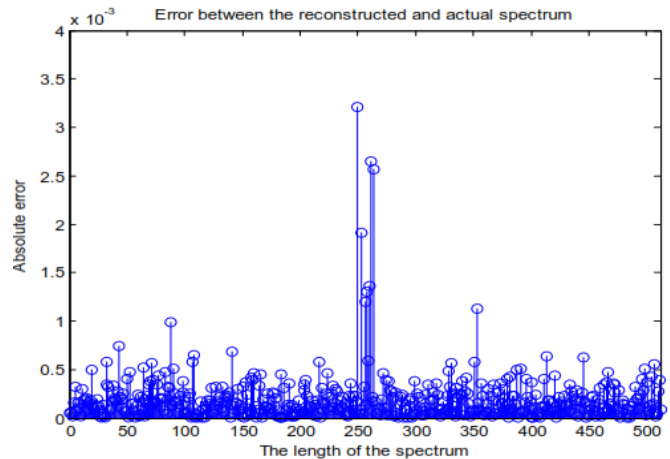


Figure 6. Error between the reconstructed and the actual spectrum

Another important property of the DCT is that all the spectral coefficients are purely real. Assuming that the input signal is periodic, the magnitude of the DFT is spatially invariant (phase of the input does not matter) which is not true for DCT. The DCT does not introduce discontinuities while imposing periodicity into the time signal, whereas in the DFT, the time signal is truncated and assumed to be periodic. As a result, discontinuities are introduced in the time domain and corresponding artefacts are introduced into the frequency domain. However, as an even symmetry is assumed while

truncating the timesignal, no discontinuities or related artefacts are introduced in the DCT. The comparison between the FFT and the DCT is shown in Figure 10 [8].

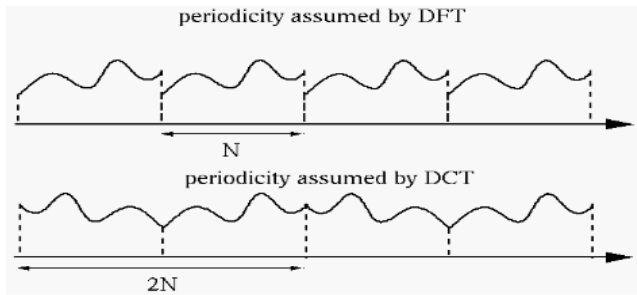


Figure 7. Periodicity comparison of DFT and DCT [8]

In order to test the algorithm on a real speech signal, a wave recorder was used to record a short piece of speech. The MATLAB function “wavrecord” allows the user to record n samples of an audio signal at a specific sample rate. For instance, Figure 8, shows a speech signal recorded using the “wavrecord” function composed of 2000 samples. The recorded speech signal then goes through the DCT which transforms a sequence of real data points into its real spectrum. The transformed speech signal is shown in Figure 9. Before compressive sensing is applied to the DCT spectrum a threshold window is used to eliminate the small coefficients.

Table 1. Amount of compression by varying signal parameter.

Length of Signal (L)	Threshold window (Th)		Compressed samples (K)	Error (err)	Compression (%) (KL)
	UL	LL			
2000	0.04	-0.06	1000	$1.5 \times 10^{-5}$	50
2000	0.04	-0.06	900	$1.8 \times 10^{-5}$	55
2000	0.04	-0.06	800	$7 \times 10^{-5}$	60
2000	0.04	-0.06	700	0.7	65
2000	0.04	-0.06	600	0.18	70
2000	0.04	-0.06	500	0.3	75

#### IV. SPEECH SIGNAL VARIATION

The rationale under this process is that the small coefficient does not contribute to the overall signal compared to the large coefficient. This is used to ensure that the DCT spectrum is sparse before applying compressive sensing. The result from this process is shown in Figure 7. The threshold spectrum is then multiplied by the measurement matrix which in this case is composed of randomly generated numbers which is shown in Figure 11.

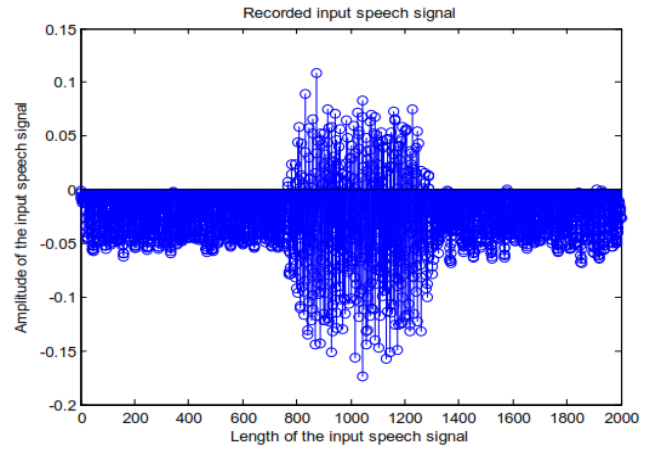


Figure 8. Recorded input speech signal

The output of compressive sensing is the observation vector which is sent to the mobile communication module in order to be transmitted which is shown in Figure 12. At the receiver the compressed DCT coefficient is decompressed and reconstructed from a significant small number of observations using one of the different optimization techniques such as the  $l_1$  normalization shown in Figure 16.

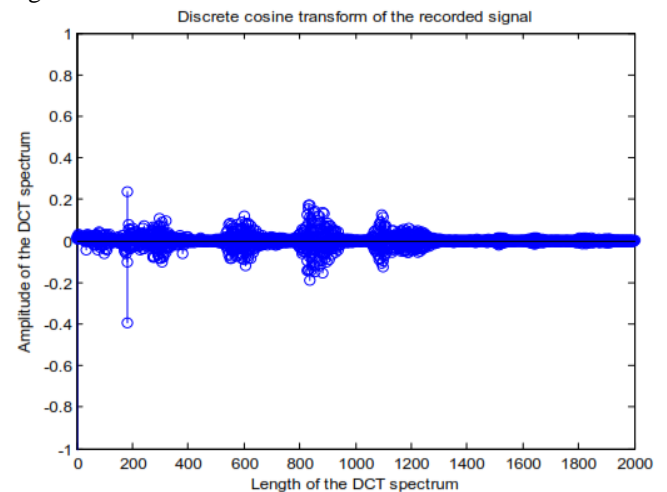


Figure 9. DCT of recorded speech signal

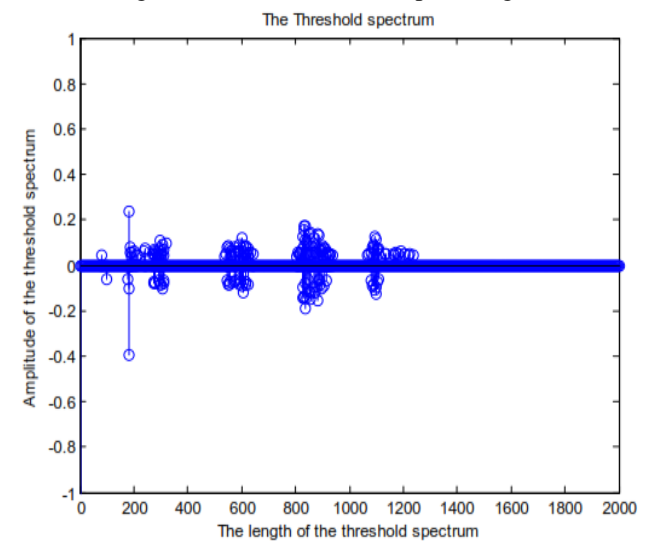


Figure 10. Threshold spectrum

In this research the design of a new mobile communication system using compressive sensing has been studied. The proposed system should fulfil the following specifications:

- Low power consumption
- Accurate reconstruction of the speech signal
- Increased data rates

During the design process, this module went through different tests and analysis in order to find the most adequate optimization technique to reconstruct the speech signal with few random measurements without losing the information. For simulation purposes, code was created in order to compress and transmit the speech signal below the Nyquist rate by taking only a few measurements of the signal. The result shows that by keeping the length of the signal ( $L$ ) and threshold window ( $Th$ ) constant one can achieve the desired compression of the signal by making the signal sparse ( $K$ ) to a certain amount which in turn increases the data rates.

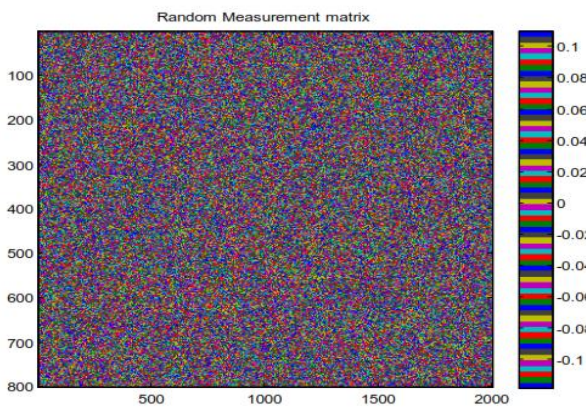


Figure 11. Random measurement matrix

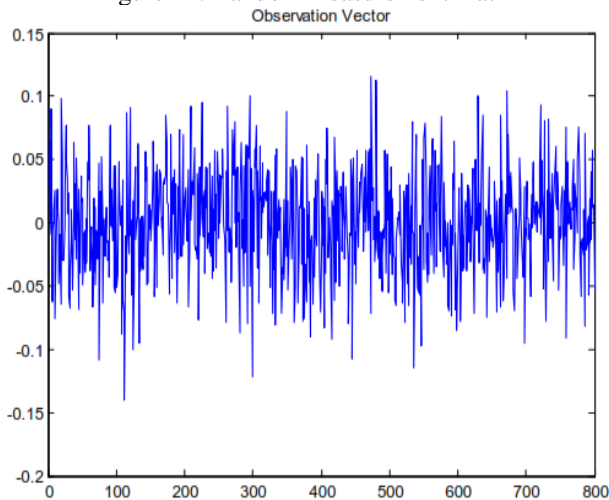


Figure 12. Observation vector

The error is calculated by taking the difference between the received and the transmitted threshold spectrum, which is shown in Figure 14. Finally, the received reconstructed spectrum is passed through the IDCT in order to recover the speech signal. The recovered speech signal can be observed in Figure 15. During the design of the proposed system multiple tests were performed in order to analyze the efficiency of this system.

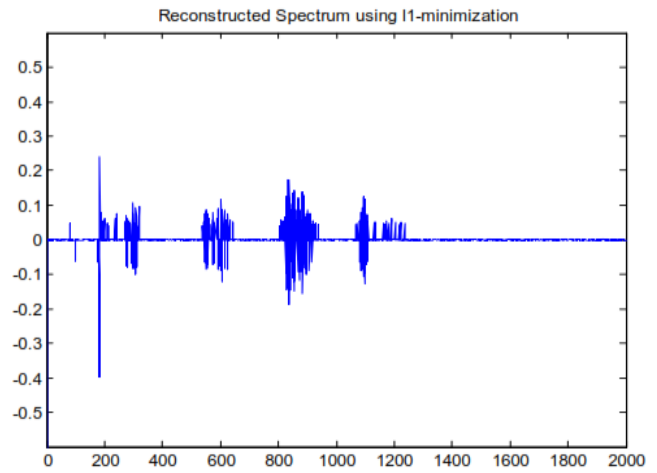


Figure 13. Reconstructed spectrum using  $l_1$

Table 1 shows how the length of the signal, the threshold value and the sparsity of the signal affect the compression rates. It is also observed that by keeping the length of the signal ( $L$ ) constant and by varying the Threshold window ( $Th$ ) it is plausible to achieve a desired compression. This is because by modifying the threshold window the compressed sample ( $K$ ) is also modified

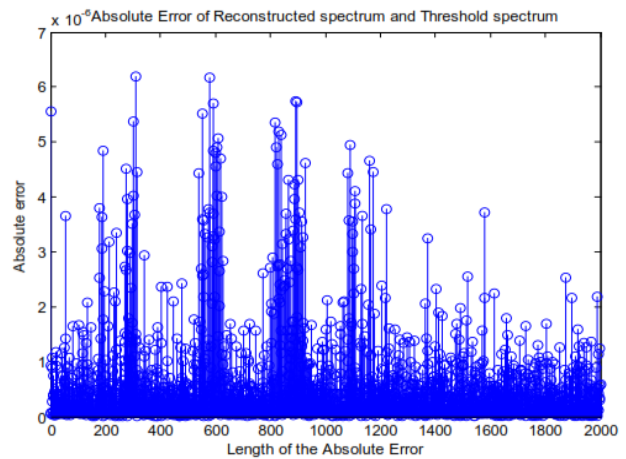


Figure 14. Absolute error between the received reconstructed spectrum and original Spectrum

## V. CONCLUSION

Two different types of measurement matrices: predefined and random measurement matrices were studied and tested using MATLAB. The speech signal was reconstructed without losing important information in order to achieve an increase in the data rates. After multiple simulations, it was found that the system worked as expected and the speech signal was reconstructed efficiently with a minimum error. However, the system is still not perfect and more research still required. Performance of compressive sensing is better when compared to wavelet compression as there is a minimum error with same compression rate using different parameters.

## REFERENCES

[1]. D.L. Donoho, "Compressed Sensing," IEEE Transactions on Information Theory, vol. 52, pp.1289-1306, 2006.

- [2]. M. Vetterli, P. Marziliano, and T. Blu, "Sampling Signals with Finite Rate of Innovation," *IEEE Transaction on Signal Process*, vol. 50, no. 6, pp.1417–1428,2002.
- [3]. E. Candes, J. Romberg, and T. Tao, "Robust Uncertainty Principles: Exact Signal Reconstruction from Highly Incomplete Frequency Information," *IEEE Transaction on Information Theory*, vol. 52, pp. 489–509, 2006.
- [4]. E. Candes and J. Romberg, "Practical Signal Recovery from Random Projections," *Processing SPIE International Symposium Electronic Imaging*, pp. 76–86, vol. 5674, 2005.
- [5]. R. Baraniuk and P. Steeghs, "Compressive Radar Imaging," *Radar Conference, 2007 IEEE*, doi:10.1109/RADAR.2007, pp.128-133, 2007.
- [6]. E. Candes and T. Tao. "Near-optimal Signal Recovery from Random Projections and universal encoding strategies," *IEEE*, vol. 52, pp. 5406 – 5425, 2004.
- [7]. S.M. Kay. *Fundamentals of statistical signal processing*. Prentice Hall, 1998.
- [8]. M.A. Davenport, M.B.Wakin, and R.G. Baraniuk. *Detection and Estimation with Compressive Measurements*. Technical report, Department of Electrical and Computer Engineering, Rice University, 2006.
- [9].